

Inverse problems for elliptic equations

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in Inverse Problems Research

1 Inverse problem in applications

Calderón's inverse problem: Measure electric resistance between all boundary points of a body. Can the conductivity be determined in the body?

Inverse problem for the wave equation: Let us send waves from the boundary of a body and measure the waves at the boundary. Can the wave speed be determined in the body?

Question: What happens if boundary is not well known?

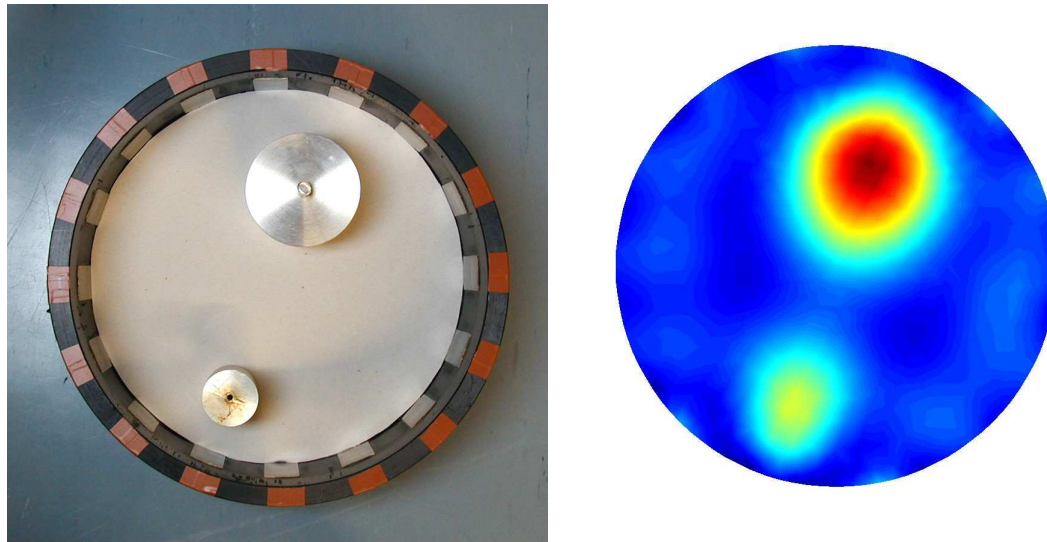


Figure: University of Kuopio.

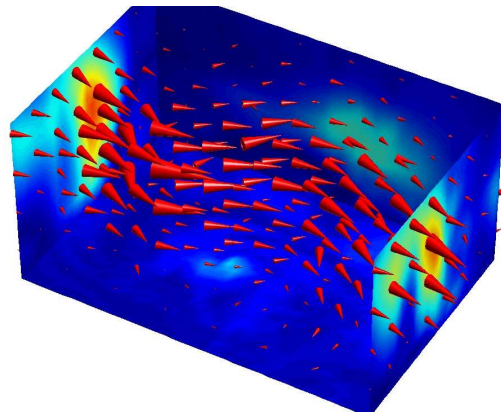
2 Inverse conductivity problem

Consider a body $\Omega \subset \mathbb{R}^n$. An electric potential $u(x)$ causes the current

$$J(x) = \sigma(x) \nabla u(x).$$

Here the conductivity $\sigma(x)$ can be an **isotropic**, that is, scalar, or an **anisotropic**, that is, matrix valued function. If the current has no sources inside the body, we have

$$\nabla \cdot \sigma(x) \nabla u(x) = 0.$$



Conductivity equation

$$\begin{aligned}\nabla \cdot \sigma(x) \nabla u(x) &= 0 \quad \text{in } \Omega, \\ u|_{\partial\Omega} &= f.\end{aligned}$$

Calderón's inverse problem: Do the measurements made on the boundary determine the conductivity, that is, does $\partial\Omega$ and the **Dirichlet-to-Neumann map** Λ_σ ,

$$\Lambda_\sigma(f) = \nu \cdot \sigma \nabla u|_{\partial\Omega}$$

determine the conductivity $\sigma(x)$ in Ω ?

Some previous results for inverse conductivity problem:

- Calderón 1980: Solution of the linearized inverse problem.
- Sylvester-Uhlmann 1987: Uniqueness of inverse problem in \mathbb{R}^n , $n \geq 3$
- Nachman 1996: Calderón's problem in \mathbb{R}^2
- Astala-Päivärinta 2003: Uniqueness of Calderón's problem in \mathbb{R}^2 with L^∞ -conductivity
- Sylvester 1990: Inverse problem for an anisotropic conductivity near constant in \mathbb{R}^2 .
- Siltanen-Mueller-Isaacson 2000: Explicit numerical solution for the 2D-inverse problem.
- Kenig-Sjöstrand-Uhlmann 2006: Reconstructions with limited data.

What happens when the following standard assumptions are not valid?

- The boundary $\partial\Omega$ is known.
- Topology of Ω is known.
- Conductivity satisfies

$$C_0 \leq \gamma(x) \leq C_1, \quad C_0, C_1 > 0.$$

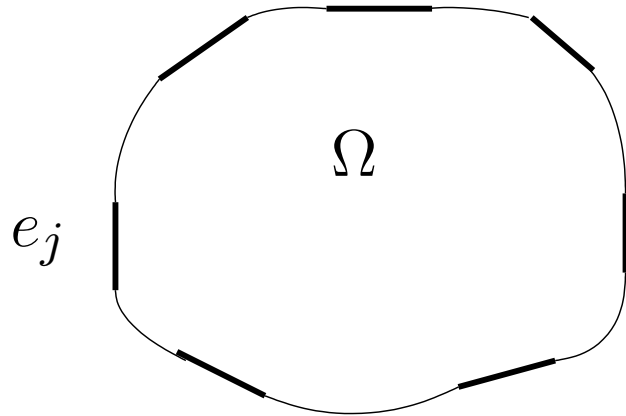
3 Electrical Impedance Tomography with an unknown boundary

Practical task: In medical imaging one often wants to find an image of the conductivity, when the domain Ω is poorly known.



Figure: Rensselaer Polytechnic Institute.

Complete electrode model. Let $e_j \subset \partial\Omega$, $j = 1, \dots, J$ be disjoint open sets (electrodes) and



$$\begin{aligned} \nabla \cdot \gamma \nabla v &= 0 \quad \text{in } \Omega, \\ z_j \nu \cdot \gamma \nabla v + v|_{e_j} &= V_j, \\ \nu \cdot \gamma \nabla v|_{\partial\Omega \setminus \cup_{j=1}^J e_j} &= 0. \end{aligned}$$

Here z_j are the contact impedance of electrodes and $V_j \in \mathbb{R}$. The boundary measurements are the currents

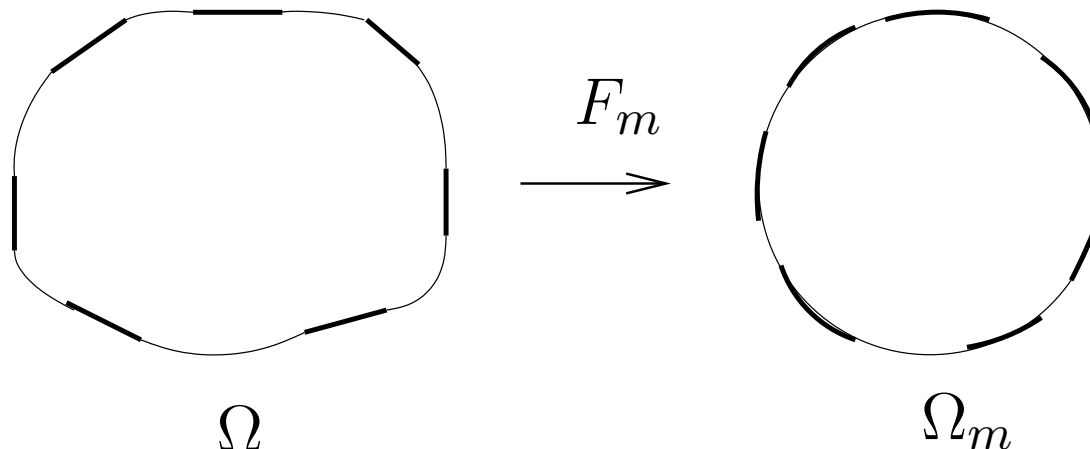
$$I_j = \frac{1}{|e_j|} \int_{e_j} \nu \cdot \gamma \nabla v(x) \, ds(x), \quad j = 1, \dots, J.$$

The matrix $E : (V_j)_{j=1}^J \rightarrow (I_j)_{j=1}^J$ is the **electrode measurement matrix**.

Mathematical formulation of EIT with unknown boundary:

1. Assume that γ is an isotropic conductivity in Ω .
2. Assume that we are given a set Ω_m that is our best guess for Ω . Let $F_m : \Omega \rightarrow \Omega_m$ be a map corresponding to the modeling error.
3. The given data is the electrode measurement matrix $E \in \mathbb{R}^{J \times J}$.

Fact: The deformation $F_m : \Omega \rightarrow \Omega_m$ can change an isotropic conductivity to an anisotropic conductivity.



4 Anisotropic inverse problems

- Non-uniqueness.
- Invariant formulation. Uniqueness and non-uniqueness results
- Applications to Euclidean space: non-uniqueness results.

Deformation of the domain. Assume that

$$\gamma(x) = (\gamma^{jk}(x)) \in \mathbb{R}^{n \times n},$$

$$\nabla \cdot \gamma \nabla u = 0 \quad \text{in } \Omega.$$

Let F be diffeomorphism

$$F : \Omega \rightarrow \Omega, \quad F|_{\partial\Omega} = Id.$$

Then

$$\nabla \cdot \tilde{\gamma} \nabla v = 0 \quad \text{in } \Omega,$$

where

$$v(x) = u(F^{-1}(x)), \quad \tilde{\gamma}(y) = F_* \gamma(y) = \frac{(DF) \cdot \gamma \cdot (DF)^t}{\det(DF)} \Big|_{x=F^{-1}(y)}$$

Then $\Lambda_{\tilde{\gamma}} = \Lambda_{\gamma}$.

Invariant formulation.

Assume $n \geq 3$. Consider Ω as a Riemannian manifold with

$$g^{jk}(x) = (\det \gamma(x))^{-1/(n-2)} \gamma^{jk}(x).$$

Then conductivity equation is the Laplace-Beltrami equation

$$\Delta_g u = 0 \quad \text{in } \Omega, \quad \text{where}$$

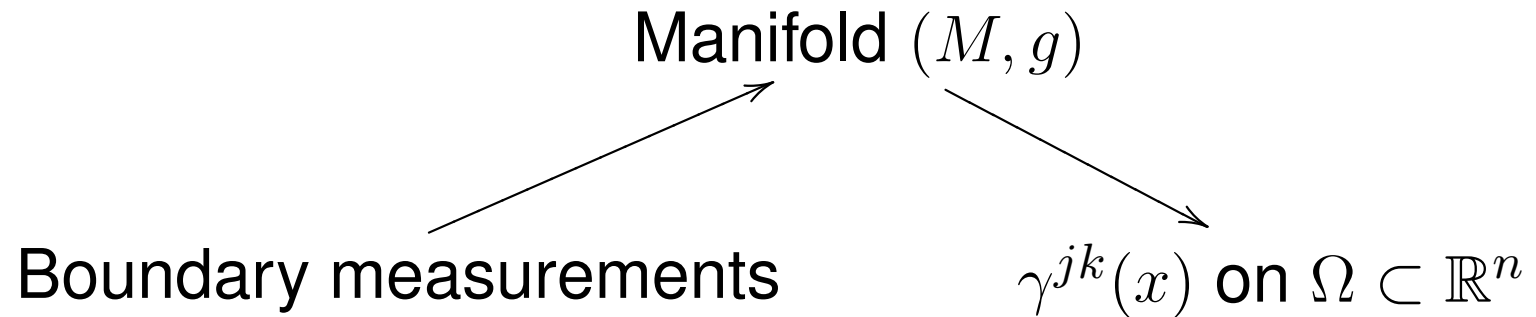
$$\Delta_g u = \sum_{j,k=1}^n g^{-1/2} \frac{\partial}{\partial x^j} \left(g^{1/2} g^{jk} \frac{\partial}{\partial x^k} u \right)$$

and $g = \det(g_{ij})$, $[g_{ij}] = [g^{jk}]^{-1}$.

Inverse problem: Can we determine the Riemannian manifold (M, g) by knowing ∂M and

$$\Lambda_{M,g} : u|_{\partial M} \mapsto \partial_\nu u|_{\partial M}.$$

Generally, solutions of anisotropic inverse problems are not unique. However, if we have enough a priori knowledge of the form of the conductivity, we can sometimes solve the inverse problem uniquely.



Uniqueness results

Theorem 1 (L.-Taylor-Uhlmann 2003) *Assume that (M, g) is a complete n -dimensional real-analytic Riemannian manifold and $n \geq 3$. Then ∂M and*

$$\Lambda_{M,g} : u|_{\partial M} \mapsto \partial_\nu u|_{\partial M}$$

determine (M, g) uniquely.

Theorem 2 (L.-Uhlmann 2001) *Assume that (M, g) is a compact 2-dimensional Riemannian manifold. Then ∂M and*

$$\Lambda_{M,g} : u|_{\partial M} \mapsto \partial_\nu u|_{\partial M}$$

determine conformal class

$$\{(M, \alpha g) : \alpha \in C^\infty(M), \alpha(x) > 0\}$$

uniquely.

5 Anisotropic problem in $\Omega \subset \mathbb{R}^2$.

Isotropic case:

Theorem 3 (Astala-Päivärinta 2003) *Let $\Omega \subset \mathbb{R}^2$ be a simply connected bounded domain and $\sigma \in L^\infty(\Omega; \mathbb{R}_+)$ an isotropic conductivity function. Then the Dirichlet-to-Neumann map Λ_σ for the equation*

$$\nabla \cdot \sigma \nabla u = 0$$

determines uniquely the conductivity σ .

Next we denote $\sigma \in \Sigma(\Omega)$ if $\sigma(x) \in \mathbb{R}^{2 \times 2}$ is symmetric, measurable, and

$$C_1 I \leq \sigma(x) \leq C_2 I, \quad \text{for a.e. } x \in \Omega$$

with some $C_1, C_2 > 0$.

Sylvester 1990, Sun-Uhlmann 2003, Astala-L.-Päivärinta 2005

Theorem 4 *Let $\Omega \subset \mathbb{R}^2$ be a simply connected bounded domain and $\sigma_1, \sigma_2 \in L^\infty(\Omega; \mathbb{R}^{2 \times 2})$ conductivity tensors. If $\Lambda_{\sigma_1} = \Lambda_{\sigma_2}$ then there is a $W^{1,2}$ -diffeomorphism*

$$F : \Omega \rightarrow \Omega, \quad F|_{\partial\Omega} = Id$$

such that

$$\sigma_1 = F_*\sigma_2.$$

Recall that if $F : \Omega \rightarrow \tilde{\Omega}$ is a diffeomorphism, it transforms the conductivity σ in Ω to $\tilde{\sigma} = F_*\sigma$ in $\tilde{\Omega}$,

$$\tilde{\sigma}(x) = \frac{DF(y) \sigma(y) (DF(y))^t}{|\det DF(y)|} \Big|_{y=F^{-1}(x)}$$

Proof. Identify $\mathbb{R}^2 = \mathbb{C}$. Let σ be an anisotropic conductivity, $\sigma(x) = I$ for $x \in \mathbb{C} \setminus \Omega$. There is $F : \mathbb{C} \rightarrow \mathbb{C}$ such that

$$\gamma = F_*\sigma$$

is isotropic. There are $w(x, k)$ such that

$$\nabla \cdot \gamma \nabla w = 0 \text{ in } \mathbb{C}$$

and

$$\lim_{x \rightarrow \infty} w(x, k) e^{-ikx} = 1, \quad \lim_{k \rightarrow \infty} \frac{1}{k} \log(w(x, k) e^{-ikx}) = 0.$$

Let $u(x, k) = w(F^{-1}(x), k)$. The Λ_σ determines $u(x, k)$ for $x \in \mathbb{C} \setminus \Omega$ and

$$F^{-1}(x) = \lim_{k \rightarrow \infty} \frac{\log u(x, k)}{ik}, \quad x \in \mathbb{C} \setminus \Omega.$$

Corollaries:

1. Inverse problem in the half space.

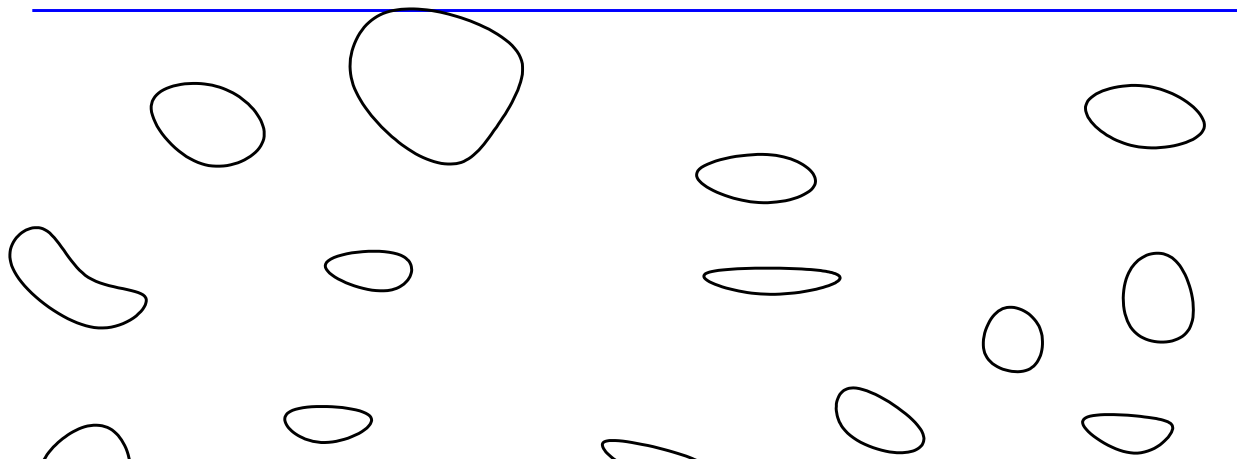
Let $\sigma \in C^\infty(\mathbb{R}_-^2)$ satisfy $0 < C_1 \leq \sigma \leq C_2$ and

$$\nabla \cdot \sigma \nabla u = 0 \quad \text{in } \mathbb{R}_-^2 = \{(x^1, x^2) \mid x^2 < 0\}, \quad (1)$$

$$u|_{\partial\mathbb{R}_-^2} = f, \quad u \in L^\infty(\mathbb{R}_-^2). \quad (2)$$

Notice that here the radiation condition at infinity (2) is quite simple. Let

$$\Lambda_\sigma : H_{comp}^{1/2}(\partial\mathbb{R}_-^2) \rightarrow H^{-1/2}(\partial\mathbb{R}_-^2), \quad f \mapsto \nu \cdot \sigma \nabla u|_{\partial\mathbb{R}_-^2}.$$

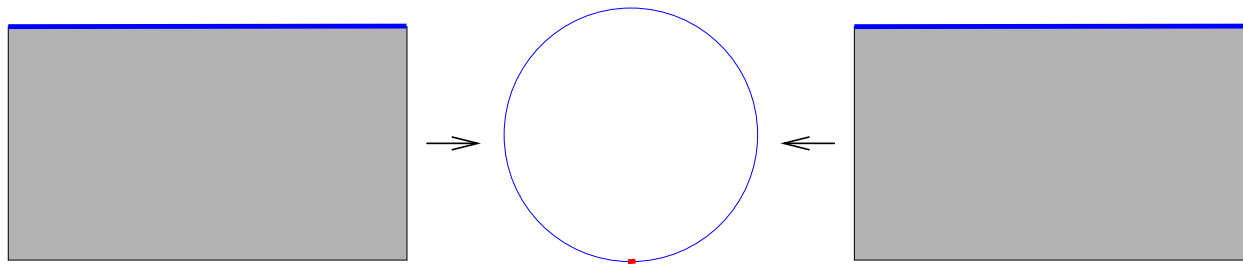


Corollary 5.1 (Astala-L.-Päivärinta 2005) *The map Λ_σ determines the equivalence class*

$$E_\sigma = \{ \sigma_1 \in \Sigma(\mathbb{R}_-^2) \mid \sigma_1 = F_*\sigma, F : \mathbb{R}_-^2 \rightarrow \mathbb{R}_-^2 \text{ is } W^{1,2}\text{-diffeo, } F|_{\partial\mathbb{R}_-^2} = I \}.$$

Moreover, each class E_σ contains at most one isotropic conductivity.

Thus, if σ is known to be isotropic, it is determined uniquely by Λ_σ .



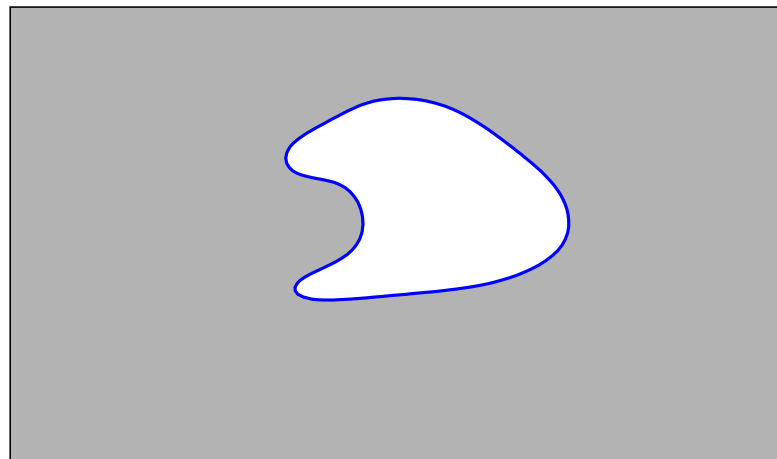
Open problem: Inverse problem in \mathbb{R}_+^3 .

2. Inverse problem in the exterior domain. Let $S = \mathbb{R}^2 \setminus \overline{D}$, where D is a bounded Jordan domain. Let

$$\begin{aligned}\nabla \cdot \sigma \nabla u &= 0 \quad \text{in } S, \\ u|_{\partial S} &= f \in H^{1/2}(\partial S), \\ u &\in L^\infty(S).\end{aligned}$$

We define

$$\Lambda_\sigma : H^{1/2}(\partial S) \rightarrow H^{-1/2}(\partial S), \quad f \mapsto \nu \cdot \sigma \nabla u|_{\partial S}.$$



Let $S \subset \mathbb{R}^2$, $\mathbb{R}^2 \setminus S$ compact, and denote $\bar{S} = S \cup \{\infty\}$.

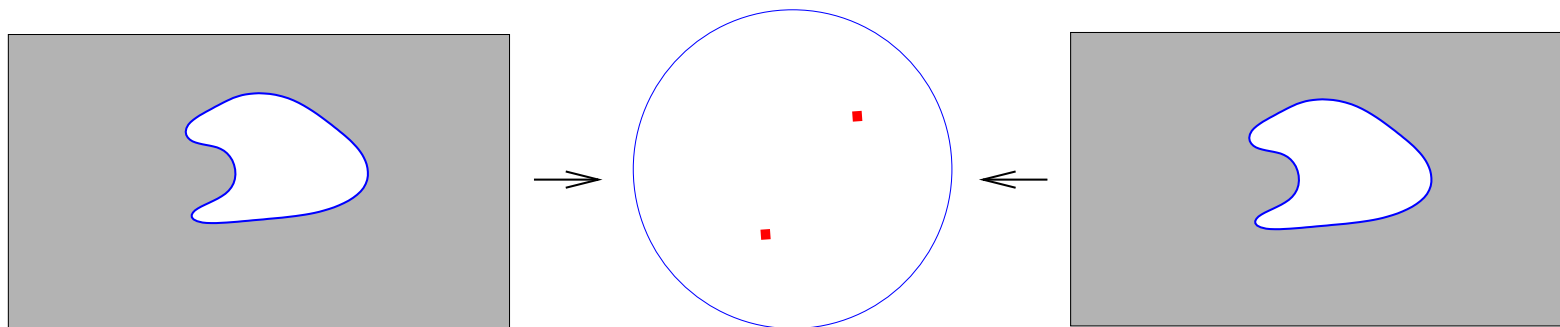
Corollary 5.2 (Astala-L.-Päivärinta 2005) *Let $\sigma \in \Sigma(S)$.*

Then the map Λ_σ determines the equivalence class

$$E_{\sigma,S} = \{ \sigma_1 \in \Sigma(S) \mid \sigma_1 = F_*\sigma, F : \bar{S} \rightarrow \bar{S} \text{ is a } W^{1,2}\text{-diffeo,} \\ F|_{\partial S} = I \}.$$

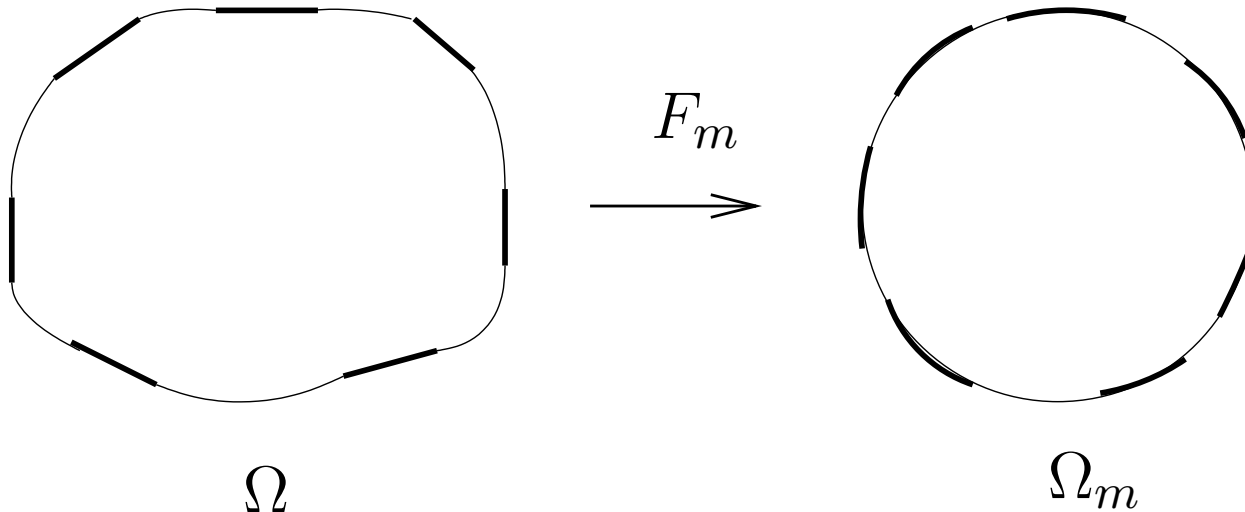
Moreover, if σ is known to be isotropic, it is determined uniquely by Λ_σ .

The group of diffeomorphisms preserving the data do not map $S \rightarrow S$.

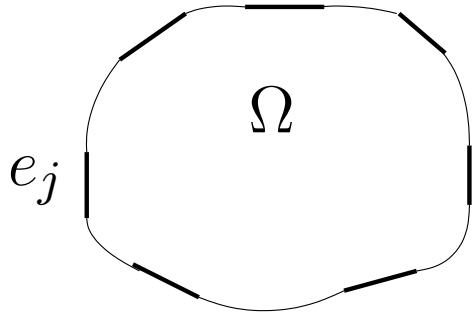


6 Unknown boundary problem in \mathbb{R}^2 .

1. Assume that γ is an isotropic conductivity in Ω .
2. Assume that we are given a set Ω_m that is our best guess for Ω . Let $F_m : \Omega \rightarrow \Omega_m$ be a map corresponding to the modeling error.
3. We are given the electrode measurement matrix $E \in \mathbb{R}^{J \times J}$.



Complete electrode model Let $e_j \subset \partial\Omega$, $j = 1, \dots, J$ be disjoint open sets (electrodes) and



$$\begin{aligned} \nabla \cdot \gamma \nabla v &= 0 \quad \text{in } \Omega, \\ z_j \nu \cdot \gamma \nabla v + v|_{e_j} &= V_j, \\ \nu \cdot \gamma \nabla v|_{\partial\Omega \setminus \cup_{j=1}^J e_j} &= 0, \end{aligned}$$

where z_j are the **contact impedances** and V_j are the potentials on electrode e_j . Measure currents

$$I_j = \frac{1}{|e_j|} \int_{e_j} \nu \cdot \gamma \nabla v(x) \, ds(x), \quad j = 1, \dots, J.$$

This give us electrode measurements matrix $E : \mathbb{R}^J \rightarrow \mathbb{R}^J$, $E(V_1, \dots, V_J) = (I_1, \dots, I_J)$.

Continuous model. The electrical potential u satisfy

$$\begin{aligned}\nabla \cdot \gamma \nabla u &= 0, & x \in \Omega, \\ (z\nu \cdot \gamma \nabla u + u)|_{\partial\Omega} &= h,\end{aligned}$$

where γ is an isotropic conductivity and z is the contact impedance on the boundary.

Boundary measurements are modeled by the **Robin-to-Neumann map** $R = R_{\gamma,z}$ given by

$$R_{\gamma,z} : h \mapsto \nu \cdot \gamma \nabla u|_{\partial\Omega}$$

The power needed to maintain the given voltage (V_1, \dots, V_J) or h at boundary are given by

$$p(V) = E[V, V], \quad p(h) = R[h, h],$$

where we have quadratic forms

$$E[V, \tilde{V}] = \sum_{j=1}^J (EV)_j \tilde{V}_j |e_j|, \quad R[h, \tilde{h}] = \int_{\partial\Omega} (Rh) \tilde{h} ds.$$

The form $E[\cdot, \cdot]$ can be viewed as a discretization of $R[\cdot, \cdot]$.

Let $F_m : \Omega \rightarrow \Omega_m$ be deformation of the domain and $f_m = F_m|_{\partial\Omega}$. On $\partial\Omega_m$ we define

$$\tilde{R} = (f_m)_* R_{\gamma,z}.$$

Then the quadratic form R corresponding to the power needed to have the given voltage on the boundary satisfies

$$\tilde{R}[h, h] = R[h \circ f_m, h \circ f_m], \quad h \in H^{-1/2}(\partial\Omega_m).$$

Thus the electrode measurement matrix on $\partial\Omega_m$ corresponds in the continuous model to the map

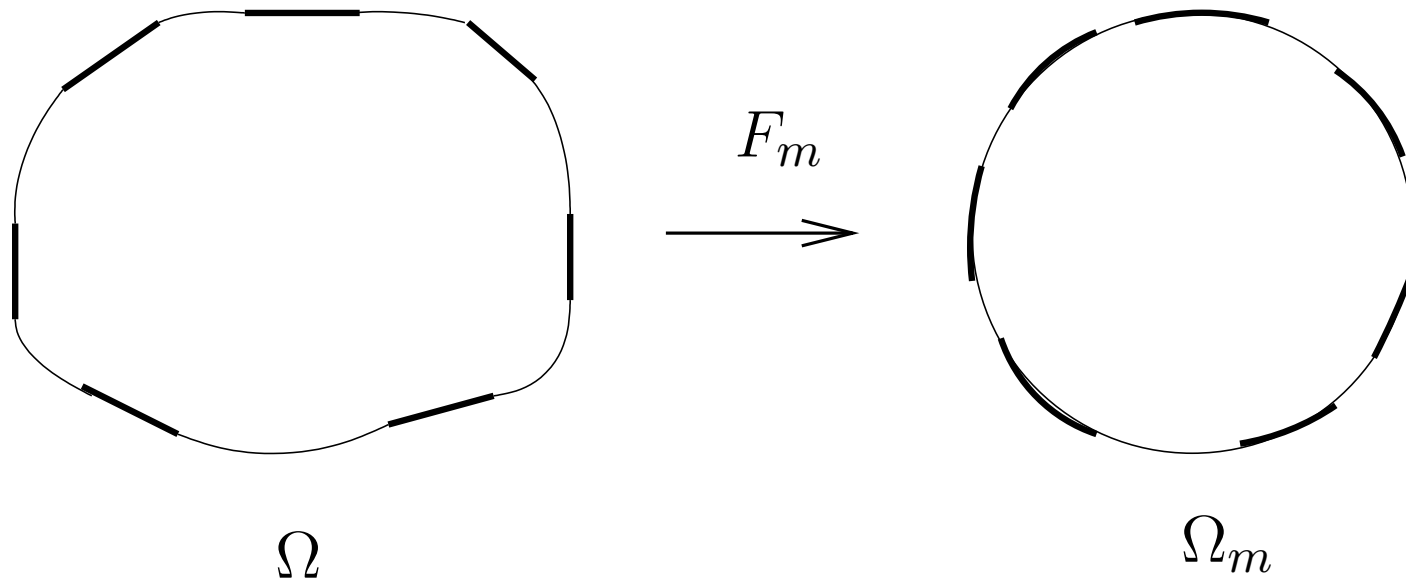
$$\tilde{R} = (f_m)_* R_{\gamma,z}.$$

Fact: $\tilde{R} = R_{\tilde{\gamma},\tilde{z}}$ where

$$\tilde{\gamma} = (F_m)_* \gamma, \quad \tilde{z} = (F_m)_* z.$$

Thus the boundary map \tilde{R} on $\partial\Omega_m$ is equal to $R_{\tilde{\gamma}, \tilde{z}}$ that corresponds to boundary measurements made with an **anisotropic** conductivity $\tilde{\gamma} = (F_m)_*\gamma$ in Ω_m and $\tilde{z} = z \circ f_m^{-1}$.

Assume we are given Ω_m and \tilde{R} . Our aim is to find a conductivity tensor in Ω_m that is as close as possible to an isotropic conductivity and has the Robin-to-Neumann map \tilde{R} .

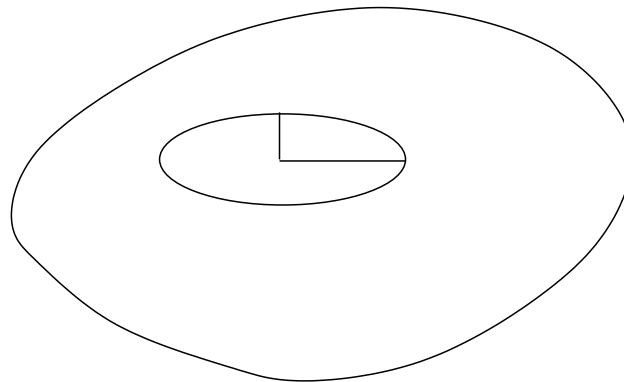


Definition 6.1 Let $\gamma = \gamma^{jk}(x)$ be a matrix valued conductivity. Let $\lambda_1(x)$ and $\lambda_2(x)$, $\lambda_1(x) \geq \lambda_2(x)$ be its eigenvalues. Anisotropy of γ at x is

$$K(\gamma, x) = \left(\frac{\lambda_1(x) - \lambda_2(x)}{\lambda_1(x) + \lambda_2(x)} \right)^{1/2}.$$

The *maximal anisotropy* of γ in Ω is

$$K(\gamma) = \sup_{x \in \Omega} K(\gamma, x).$$



The anisotropy function $K(\widehat{\gamma}, x)$ is constant for

$$\widehat{\gamma}(x) = \eta(x) R_{\theta(x)} \begin{pmatrix} \lambda^{1/2} & 0 \\ 0 & \lambda^{-1/2} \end{pmatrix} R_{\theta(x)}^{-1}$$

where

$$\lambda \geq 1,$$

$$\eta(x) \in \mathbb{R}_+,$$

$$R_{\theta} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

We say that $\widehat{\gamma} = \widehat{\gamma}_{\lambda, \theta, \eta}$ is a **uniformly anisotropic conductivity**.

Theorem 6.2 (Kolehmainen-L.-Ola 2005) *Let $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected $C^{1,\alpha}$ -domain, $\gamma \in L^\infty(\overline{\Omega}, \mathbb{R})$ be isotropic conductivity, and $z \in C^1(\partial\Omega)$ be the contact impedance.*

Let Ω_m be a model domain and $f_m : \partial\Omega \rightarrow \partial\Omega_m$ be a $C^{1,\alpha}$ -diffeomorphism.

Assume that we know $\partial\Omega_m$ and $\tilde{R} = (f_m)_ R_{\gamma,z}$. These data determine $\tilde{z} = z \circ f_m^{-1}$ and an anisotropic conductivity σ on Ω_m such that*

1. $R_{\sigma,\tilde{z}} = \tilde{R}$.
3. *If σ_1 satisfies $R_{\sigma_1,\tilde{z}} = \tilde{R}$ then $K(\sigma_1) \geq K(\sigma)$.*

Moreover, the conductivity σ is uniformly anisotropic.

Algorithm:

In following, we assume that $z = 0$ and denote $R_\sigma = R_{\sigma,z}$. The conductivity $\sigma = \hat{\gamma}_{\lambda,\eta,\theta}$ can be obtained by solving the minimization problem

$$\min_{(\lambda,\theta,\eta) \in S} \lambda, \quad \text{where } S = \{(\lambda, \theta, \eta) : R_{\hat{\gamma}(\lambda,\theta,\eta)} = \tilde{R}\}.$$

In implementation of the algorithm we approximate this by

$$\min_{(\lambda,\theta,\eta)} \|R_{\hat{\gamma}(\lambda,\theta,\eta)} - \tilde{R}\|^2 + \varepsilon_1 |\lambda - 1|^2 + \varepsilon_2 (\|\theta\|^2 + \|\eta\|^2).$$

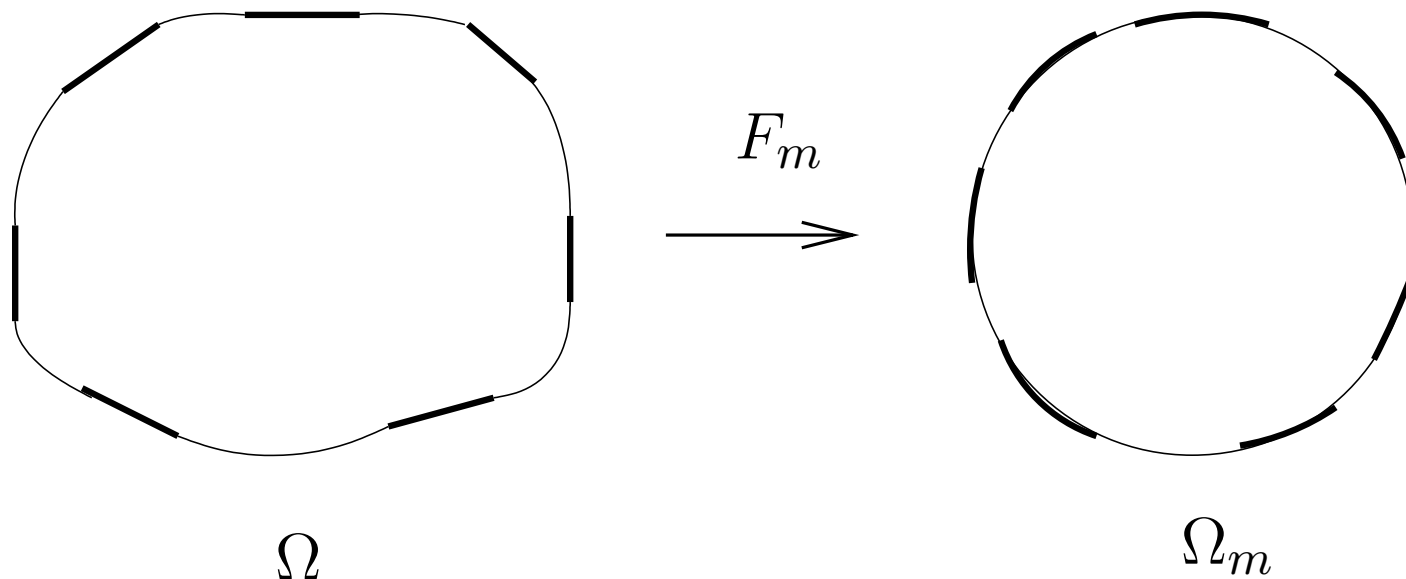
Let $f_m : \partial\Omega \rightarrow \partial\Omega_m$ be the boundary modeling map and σ be the conductivity with the smallest possible anisotropy such that $R_\sigma = \tilde{R}$. Then

Corollary 6.3 *Then there is a unique map*

$$F_e : \Omega \rightarrow \Omega_m, \quad F_e|_{\partial\Omega} = f_m$$

depending only on $f_m : \partial\Omega \rightarrow \partial\Omega_m$ such that

$$\det(\sigma(x))^{1/2} = \gamma(F_e^{-1}(x)).$$



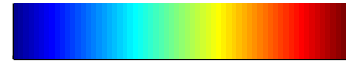
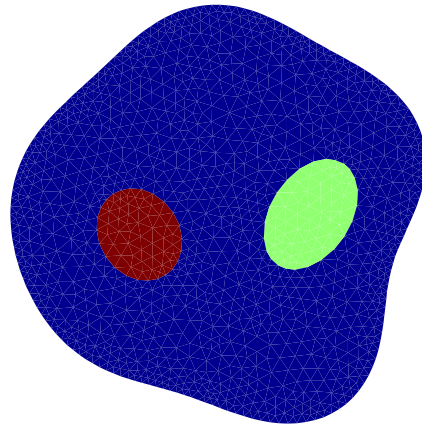
Idea of the proof. If $F : \Omega \rightarrow \Omega$ is a diffeomorphism and γ_1 is an isotropic conductivity, then

$$K(F_*\gamma_1, x) = |\mu_F(x)|$$

where

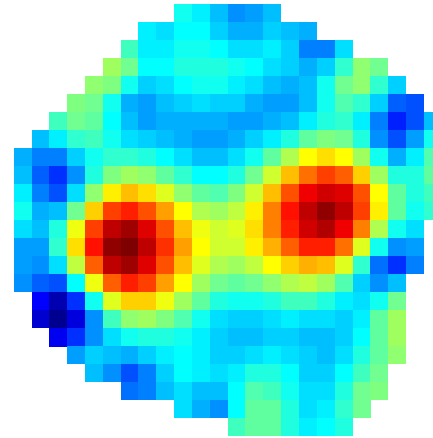
$$\mu_F = \frac{\bar{\partial}F}{\partial F}, \quad \partial = \frac{1}{2}(\partial_{x_1} - i\partial_{x_2}).$$

To find the minimally anisotropic conductivity we need to find a **quasiconformal map** with the **smallest possible dilatation** and the given boundary values. This is called the **Teichmüller map**.



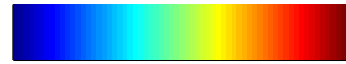
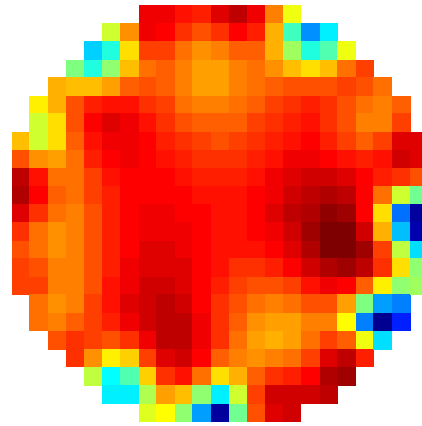
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2



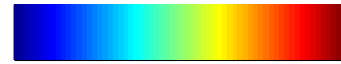
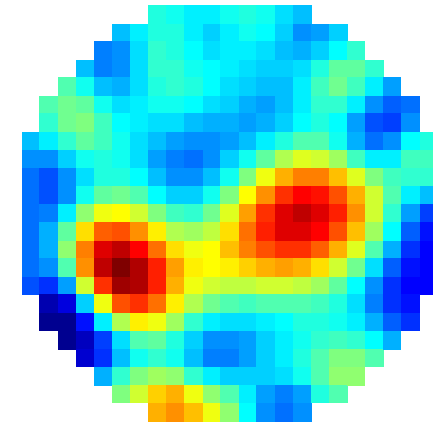
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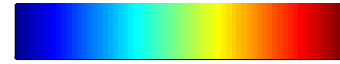
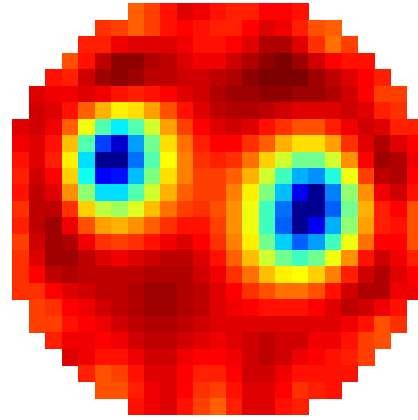
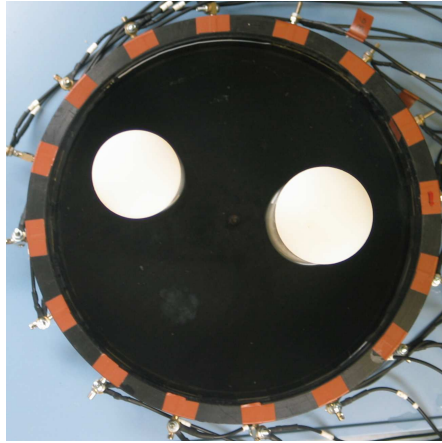
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1.3



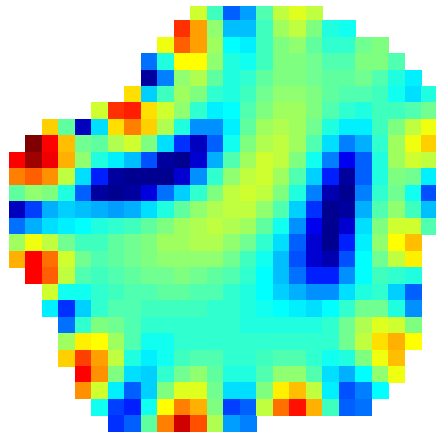
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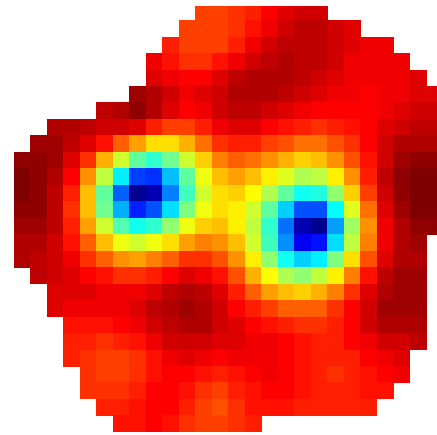
0.05

8.08



0.2

16.06



0.55

8.23

7 Unknown boundary problem in \mathbb{R}^3 .

The electrical potential u satisfies

$$\begin{aligned}\nabla \cdot \gamma \nabla u &= 0, & x \in \Omega \subset \mathbb{R}^3, \\ (z\nu \cdot \gamma \nabla u + u)|_{\partial\Omega} &= h,\end{aligned}$$

where γ is an isotropic conductivity and z is the contact impedance on the boundary.

The boundary measurements are modeled by the Robin-to-Neumann map $R = R_{z,\gamma}$ given by

$$R_{\gamma,z} : h \mapsto \nu \cdot \gamma \nabla u|_{\partial\Omega}$$

Again, let $f_m : \partial\Omega \rightarrow \partial\Omega_m$ be the modeling of boundary and $\tilde{R} = (f_m)_* R_{\gamma,z}$.

Theorem 5 (Kolehmainen-L.-Ola 2006) *Let $\Omega \subset \mathbb{R}^n$, $n \geq 3$ be a bounded, strictly convex, C^∞ -domain. Assume that $\gamma \in C^\infty(\overline{\Omega})$ is an isotropic conductivity, $z \in C^\infty(\partial\Omega)$, $z > 0$ is the contact impedance, and $R_{\gamma,z}$ is the Robin-to-Neumann map.*

Let Ω_m be a model domain and $f_m : \partial\Omega \rightarrow \partial\Omega_m$ be a diffeomorphism.

Assume that we are given $\partial\Omega_m$, the values of the contact impedance $z(f_m^{-1}(x))$, and the map $\tilde{R} = (f_m)_ R_{\gamma,z}$.*

Then we can determine Ω upto a rigid motion T and the conductivity $\gamma \circ T^{-1}$ on the reconstructed domain $T(\Omega)$.

Idea of the proof: Let γ be the isotropic conductivity on Ω , $\tilde{\gamma} = (F_m)_*\gamma$, $F_m|_{\partial\Omega} = f_m$. Let \tilde{g} be the metric in Ω_m corresponding to the conductivity $\tilde{\gamma}$.

- $\tilde{R} = R_{\tilde{\gamma}, \tilde{z}}$ determine the contact impedance \tilde{z} and the metric \tilde{g} on boundary $\partial\Omega_m$.
- $\tilde{z}(x)$ and $z(f_m^{-1}(x))$ determine $\beta = \det(Df_m^{-1})$.
- \tilde{g} and β determine $\gamma \circ f_m^{-1}$ on boundary $\partial\Omega_m$.
- On $\partial\Omega_m$ we find the metric corresponding to the Euclidean metric of $\partial\Omega$. This determines by the **Cohn-Vossen rigidity theorem** the strictly convex set Ω up to a rigid motion T .
- In $T(\Omega)$ we solve an isotropic inverse problem.

Consider now the following algorithm:

Data: Assume that we are given $\partial\Omega_m$, $\tilde{R} = (f_m)_* R_{\gamma, z}$ and $z \circ f_m^{-1}$ on $\partial\Omega_m$.

Aim: We look for a metric \tilde{g} corresponding to the conductivity $\tilde{\gamma}$ and \tilde{z} such that $\tilde{R} = R_{\tilde{\gamma}, \tilde{z}}$ and $\tilde{z} = z \circ f_m^{-1}$.

Idea: We look for a metric \tilde{g} in Ω_m and $\rho \in C^\infty(\Omega_m)$ such that

$$\bar{g}_{ij}(x) = e^{2\rho(x)} \tilde{g}_{ij}(x) \quad \text{is flat.}$$

Algorithm:

1. Determine the two leading terms in the symbolic expansion of \tilde{R} . They determine a contact impedance \hat{z} and a metric \hat{g} on $\partial\Omega_m$ such that if $\tilde{R} = R_{\tilde{\gamma}, \tilde{z}}$ then $\tilde{z} = \hat{z}$ and $\tilde{g}|_{\partial\Omega_m} = \hat{g}$.
2. Compute the ratio of reconstructed i.e. \hat{z} , and measured contact impedances

$$\beta(x) := \frac{z(f_m^{-1}(x))}{\hat{z}(x)}, \quad x \in \partial\Omega_m.$$

Then $\beta = \frac{dS_{\partial\Omega_m}}{(f_m)_* dS_{\partial\Omega}}$.

3. Let $dS_{\hat{g}}$ be the volume form of \hat{g} on $\partial\Omega_m$ and dS_E the Euclidean volume on $\partial\Omega_m$. Then

$$dS_{\hat{g}} = (\det \hat{g})^{1/2} dS_E.$$

Define

$$\hat{\gamma} = (\det \hat{g})^{1/2} \beta.$$

With this choice $\hat{\gamma}$ will satisfy $\hat{\gamma}(x) = \gamma(f_m^{-1}(x))$ for $x \in \partial\Omega_m$.

4. Define the boundary value $\hat{\rho}$ for the function ρ by

$$\hat{\rho}(x) = \frac{1}{2-n} \log(\hat{\gamma}(x)), \quad x \in \partial\Omega_m.$$

5. Solve the minimization problem

$$\min F_\tau(z, \rho, \gamma)$$

$$\begin{aligned} F_\tau(z, \rho, \gamma) &= \|\tilde{R} - R_{\gamma,z}\|_{L(H^{-1/2}(\partial\Omega_m))}^2 \\ &+ \left\| \frac{z(x)}{z(f_m^{-1}(x))} - \beta(x) \right\|_{L^2(\partial\Omega_m)} + \|\rho|_{\partial\Omega_m} - \hat{\rho}\|_{L^2(\partial\Omega_m)}^2 \\ &+ \tau \|\mathbf{C}\|_{L^2(\Omega_m)}^2 \\ &+ \sum_{i,j=1}^n \left\| \rho_{,ij} - \left(-\mathbf{Ric}_{ij} + \frac{1}{4}g_{ij}\mathbf{R} - \frac{1}{2}g_{ij}g^{lm}\rho_{,l}\rho_{,k} \right) \right\|_{L^2(\Omega_m)}^2 \end{aligned}$$

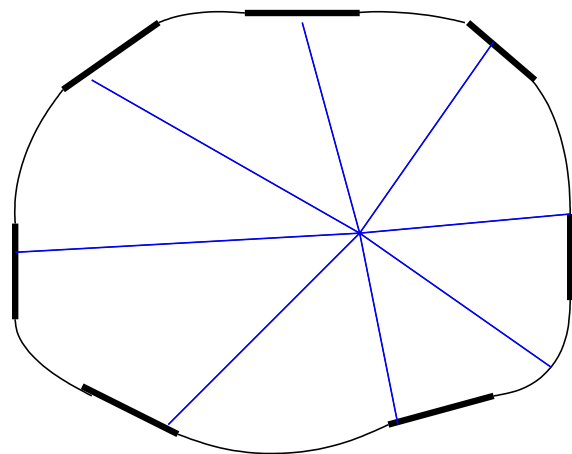
where $\tau \geq 0$, g is the metric corresponding to γ , \mathbf{Ric} and R are the Ricci curvature and scalar curvature of g , and $\mathbf{C}_{ij} = g^{kp}g^{lq}\nabla_k(\mathbf{Ric}_{li} - \frac{1}{4}Rg_{li})\epsilon_{pqj}$ is **Cotton-York tensor**.

6. Find the flat metric

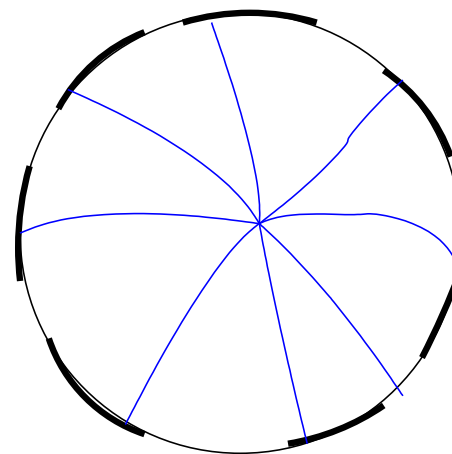
$$\bar{g}_{ij}(x) = e^{2\rho(x)} g_{ij}(x) = (F_m)_*(\delta_{ij})$$

on Ω_m and determine the geodesics with respect to the metric \bar{g} .

These give us the the embedding $F_m^{-1} : \Omega_m \rightarrow \Omega$. This gives us Ω upto a rigid motion and the conductivity γ on it.



Ω



Ω_m

Theorem 6 (Kolehmainen-L.-Ola 2006) *Let $\Omega \subset \mathbb{R}^3$ be a bounded, strictly convex, C^∞ -domain. Let $\gamma \in C^\infty(\bar{\Omega})$ is an isotropic conductivity, $z \in C^\infty(\partial\Omega)$, $z > 0$ be a contact impedance.*

Let Ω_m be a model domain and $f_m : \partial\Omega \rightarrow \partial\Omega_m$ be a C^∞ -smooth diffeomorphism.

Assume that we are given $\partial\Omega_m$, the values of the contact impedance $z(f_m^{-1}(x))$, $x \in \partial\Omega_m$, and the map $\tilde{R} = (f_m)_ R_{\gamma,z}$.*

Let $\tau \geq 0$. Then the minimizers \tilde{z} , $\tilde{\rho}$ and $\tilde{\gamma}$ of $F_\tau(\tilde{z}, \tilde{\rho}, \tilde{\gamma})$ determine Ω , z , and γ up to a rigid motion.

Inverse problems for conformally Euclidean metric.

We say that metric g is **conformally flat** if

$$g_{ij}(x) = \alpha(x)\bar{g}_{ij}(x), \quad \text{where metric } \bar{g}_{ij}(x) \text{ is flat.}$$

Open problem: Can we determine a conformally flat metric in Ω_m from its Robin-to-Neumann map?

If this is true, then one can solve the inverse problem with an unknown boundary also for non-convex domains.

8 Maxwell's equations.

In $\Omega \subset \mathbb{R}^3$ Maxwell's equations are

$$\begin{aligned}\nabla \times E &= -B_t, & \nabla \times H &= D_t, \\ D &= \epsilon(x)E, & B &= \mu(x)H \quad \text{in } \Omega \times \mathbb{R}.\end{aligned}$$

Let M be a 3-dimensional manifold and $\epsilon(x)$ and $\mu(x)$ metric tensors that are conformal to each other. Maxwell equations in time-domain are

$$\begin{aligned}dE &= -B_t, & dH &= D_t, & D &= *_{\epsilon}E, & B &= *_{\mu}H \quad \text{in } M \times \mathbb{R}, \\ E|_{t < 0} &= 0, & H|_{t < 0} &= 0,\end{aligned}$$

E, H are 1-forms, D, B are 2-forms, $*_{\epsilon}, *_{\mu}$ are Hodge-operators.

Boundary measurements:

Assume we are given $\partial\Omega$ and

$$Z : n \times E|_{\partial\Omega \times \mathbb{R}_+} \rightarrow n \times H|_{\partial\Omega \times \mathbb{R}_+},$$

Invariant formulation: Assume we are given ∂M and

$$Z : i^* E|_{\partial M \times \mathbb{R}_+} \rightarrow i^* H|_{\partial M \times \mathbb{R}_+},$$

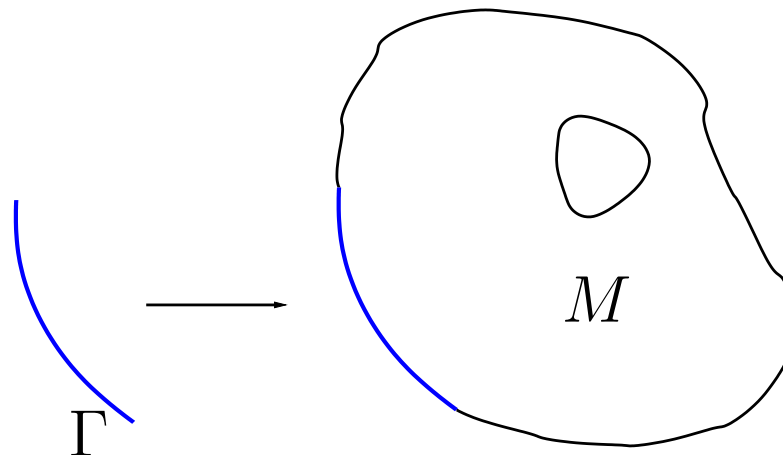
where i is the imbedding $i : \partial M \rightarrow M$.

Theorem 8.1 [Kurylev-L.-Somersalo 2005] *Let M be a compact connected 3-manifold and ϵ and μ be metric tensors conformal to each others. Assume that we are given $\Gamma \subset \partial M$ and restriction of*

$$Z_\Gamma : i^* E|_{\partial M \times \mathbb{R}_+} \rightarrow i^* H|_{\Gamma \times \mathbb{R}_+}$$

for $i^ E|_{\partial M \times \mathbb{R}_+} \in C_0^\infty(\Gamma \times \mathbb{R}_+)$. Then we can find M and ϵ, μ on M .*

Corollary 8.2 *Assume that $M \subset \mathbb{R}^3$ and ϵ and μ are scalar functions. Then Γ and Z_Γ determine uniquely (M, ϵ, μ) .*



Proof. We can focus the B -field to a single point:

Lemma 8.3 *Let $T > 0$ be a sufficiently large time. Then by using ∂M and map $Z_{\partial M}$ we can find all sequences of boundary values $i^* E_k|_{\partial M \times \mathbb{R}_+}$, $k = 1, 2, \dots$ such that for some $y \in M$ and $A \in T_y^* M$*

$$\lim_{k \rightarrow \infty} B_k(x, T) = d(A\delta_y) \quad \text{in } \mathcal{D}'(M). \quad (3)$$

The set of **focusing sequences**

$$\{(i^* E_k)_{k=1}^{\infty} : \text{the limit (3) exists}\} \subset (L^2(\partial M))^{\mathbb{Z}_+}$$

can be identified with the tangent bundle TM of M ,

$$TM = \{(y, A) : y \in M, \quad A \text{ is a tangent vector of } M \text{ at } y\}.$$

