

Estimating the Reduced Shear

- Assume we have a large number of galaxy images in a small region of the sky where we can approximate $g \approx \text{const}$. We can then estimate g from the observed ellipticities ϵ of these images, by assuming the source ellipticities ϵ^S are statistically isotropic random variables.

Assume $|g| \leq 1 \Rightarrow \epsilon(\epsilon^S) = \frac{\epsilon^S + g}{1 + g^* \epsilon^S}$

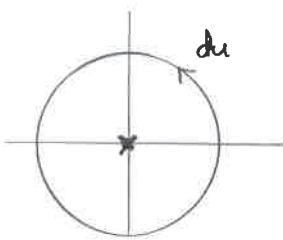
Write $\epsilon^S \equiv y e^{i2\varphi} \equiv yu$, $u = e^{i2\varphi} \Rightarrow du = 2iu d\varphi$ (u on unit circle of complex plane)

The expectation value $\langle \epsilon \rangle = \int d^2 \epsilon^S P(\epsilon^S) \epsilon(\epsilon^S)$

where the probability distribution $P(\epsilon^S) = P(y) P(\varphi)$
 $= \text{const} = \frac{1}{\pi}$ (statistical isotropy)

$\Rightarrow \langle \epsilon \rangle = \int_0^1 dy P(y) \int_0^\pi d\varphi P(\varphi) \epsilon(\epsilon^S)$, where

$\int_0^\pi d\varphi P(\varphi) \epsilon(\epsilon^S) = \frac{1}{\pi} \int_0^\pi d\varphi \frac{\epsilon^S + g}{1 + g^* \epsilon^S} = \frac{1}{2\pi i} \oint \frac{du}{u} \frac{yu + g}{1 + g^* y u}$



This is a closed integral of an analytic function in the complex plane \Rightarrow calculus of residues. There are two poles:

$u_1 = 0$

$u_2 = \frac{-1}{g^* y} \Rightarrow |u_2| = \frac{1}{|g| |y|} > 1$ outside integration contour,
 $\leq 1 < 1$

$\Rightarrow \oint = 2\pi i \text{Res}(u=0) = 2\pi i \cdot \frac{yu + g}{1 + g^* y u} \Big|_{u=0} = 2\pi i g$, independent of y

$\therefore \langle \epsilon \rangle = \int_0^1 dy P(y) \cdot \frac{1}{2\pi i} \cdot 2\pi i g = g \int_0^1 dy P(y) = \underline{g}$

1 by normalization of probability

Thus the image ellipticity is an unbiased (but noisy) estimator of the reduced shear !

- Exercise: Find $\langle \epsilon \rangle$ for the case $|g| > 1$.
- Schneider p.277: "The expectation value of κ cannot be easily calculated and depends on the intrinsic ellipticity distribution of the sources. In particular, $\langle \kappa \rangle$ is not simply related to g . However, in the limit $\kappa \ll 1$, $|g| \ll 1$, one finds $\gamma \approx g \approx \langle \epsilon \rangle \approx \frac{1}{2} \langle \kappa \rangle$."
- This simple result $\langle \epsilon \rangle = g$ is the main reason to prefer ϵ over κ .
- The noise in the estimator is determined by the same ellipticity variance

$$\sigma_{\epsilon}^2 \equiv \langle |\epsilon|^2 \rangle \quad \text{Schneider uses a reference value } \sigma_{\epsilon} \sim 0.3$$

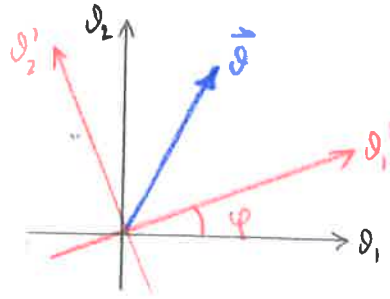
When averaging over N images, the 1σ expected error in the g estimate is $\sim \frac{\sigma_{\epsilon}}{\sqrt{N}}$

\therefore For $\Delta g \approx 0.01$, need $N \sim 1000$ galaxies

§4.3 Tangential and Cross Components

- Components of shear

Rotate the ord. axes by φ :



Here $\vec{g}, \vec{\beta}$ are abstract vector notation (independent of ord. system)

$\bar{g}, \bar{\beta}$ denote the column vectors of their components (depend on ord. system)

likewise, \bar{A} is the matrix of the components of A

$$\bar{g}' \equiv \begin{bmatrix} g_1' \\ g_2' \end{bmatrix} = \underbrace{\begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix}}_R \begin{bmatrix} g_1 \\ g_2 \end{bmatrix} = R\bar{g} \quad \text{rotation matrix } R^{-1} = R^T$$

Likewise $\bar{\beta}' = R\bar{\beta}$

Linear equation $\bar{\beta} = A\bar{g}$ (choose $\bar{\beta}_0 = \bar{g}_0 = 0$) $\Rightarrow \bar{\beta} = \bar{A}\bar{g}$ and $\bar{\beta}' = \bar{A}'\bar{g}'$

$$\Rightarrow R\bar{\beta} = \bar{A}'R\bar{g} \Rightarrow \bar{\beta} = R^{-1}\bar{A}'R\bar{g} = R^T\bar{A}'R\bar{g} \Rightarrow \bar{A} = R^T\bar{A}'R$$

$$\bar{A}' = R\bar{A}R^T$$

$$\bar{A} = (1-\chi) \begin{bmatrix} 1-g_1 & -g_2 \\ -g_2 & 1+g_1 \end{bmatrix} = (1-\chi)I + (1-\chi) \begin{bmatrix} -g_1 & -g_2 \\ -g_2 & g_1 \end{bmatrix}$$

$$\therefore \begin{bmatrix} -g_1' & -g_2' \\ -g_2' & g_1' \end{bmatrix} = \begin{bmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{bmatrix} \begin{bmatrix} -g_1 & -g_2 \\ -g_2 & g_1 \end{bmatrix} \begin{bmatrix} \cos\varphi & -\sin\varphi \\ \sin\varphi & \cos\varphi \end{bmatrix} = \dots$$

$$\Rightarrow \begin{bmatrix} -g_1' & -g_2' \\ -g_2' & g_1' \end{bmatrix} = \begin{bmatrix} -g_1 \cos 2\varphi - g_2 \sin 2\varphi & g_1 \sin 2\varphi - g_2 \cos 2\varphi \\ g_1 \sin 2\varphi - g_2 \cos 2\varphi & g_1 \cos 2\varphi + g_2 \sin 2\varphi \end{bmatrix}$$

$$\therefore g_1' = g_1 \cos 2\varphi + g_2 \sin 2\varphi$$

$$g_2' = -g_1 \sin 2\varphi + g_2 \cos 2\varphi$$

$$\text{or } \begin{bmatrix} g_1' \\ g_2' \end{bmatrix} = \begin{bmatrix} \cos 2\varphi & \sin 2\varphi \\ -\sin 2\varphi & \cos 2\varphi \end{bmatrix} \begin{bmatrix} g_1 \\ g_2 \end{bmatrix}$$

$$\text{or } g_1' + i g_2' = g_1 \cos 2\varphi + g_2 \sin 2\varphi - i g_1 \sin 2\varphi + i g_2 \cos 2\varphi$$

$$\text{Compare to } (g_1 + i g_2) e^{i 2\varphi} = (g_1 + i g_2) (\cos 2\varphi + i \sin 2\varphi) = g_1 \cos 2\varphi + i g_1 \sin 2\varphi + i g_2 \cos 2\varphi - g_2 \sin 2\varphi$$

Not this, but

$$\begin{aligned} (g_1 + i g_2) e^{-i 2\varphi} &= (g_1 + i g_2) (\cos 2\varphi - i \sin 2\varphi) = g_1 \cos 2\varphi - i g_1 \sin 2\varphi + i g_2 \cos 2\varphi + g_2 \sin 2\varphi \\ &= g_1' + i g_2' \end{aligned}$$

$$\therefore g' = g e^{-i 2\varphi}$$

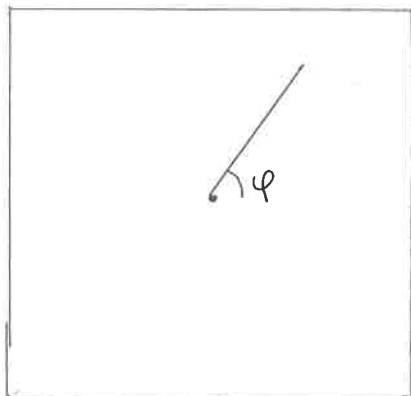
Likewise

$$y' = y e^{-i 2\varphi}$$

The same transformation properties apply to the ellipticity ϵ , ϵ^S

$$\epsilon' = \epsilon e^{-i 2\varphi}$$

- Assume now that we have a special reference direction φ , which may vary over the image plane. For example, if we have an axisymmetric lens, φ could refer to the rotation angle around the axis. (We will have other cases of a reference direction later).



Define the tangential and cross components of shear

$$\gamma_t \equiv -\gamma_1' = -\gamma_1 \cos 2\varphi - \gamma_2 \sin 2\varphi = -\text{Re}[\gamma e^{-i 2\varphi}]$$

$$\gamma_x \equiv -\gamma_2' = +\gamma_1 \sin 2\varphi - \gamma_2 \cos 2\varphi = -\text{Im}[\gamma e^{-i 2\varphi}]$$

and ellipticity

$$\epsilon_t = -\text{Re}[\epsilon e^{-i 2\varphi}]$$

$$\epsilon_x = -\text{Im}[\epsilon e^{-i 2\varphi}]$$

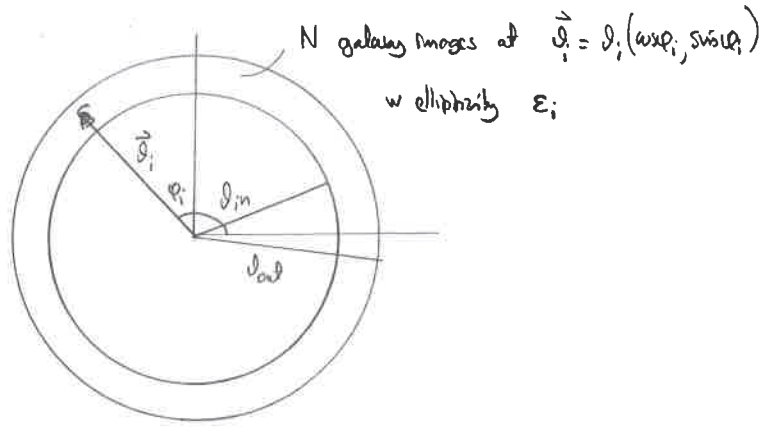
- Why the - sign? There are different sign conventions, but this one corresponds to positive γ_t stretching the image in the tangential direction (orthogonal to the φ direction) and negative γ_t in the radial direction. If we used the opposite sign convention, we should call γ_t the radial component. Notice how γ_t radial corresponds to both tangential and radial shear, whereas γ_x corresponds to shear 45° off both

Minimum Lens Strength for its WL Detection

Consider SIS $g(r) = \frac{\sigma_v^2}{2\pi G r^2}$

$\epsilon_{\pm} \equiv -\text{Re}(\epsilon_i e^{-2i\phi_i})$

$\rho_E = 4\pi \frac{D_{Ds}}{D_s} \sigma_v^2$



BS01 §4.5 $\frac{S}{N} = \frac{\rho_E}{\sigma_\epsilon} \sqrt{nm} \sqrt{\ln \frac{D_{out}}{D_{in}}}$

↑ number density of galaxies on the sky

↑ Would have to read this to understand the S/N formula [Bartelmann & Schneider, Phys. Rep. 340, 291 (2001)]

So skip this now; but the conclusion is that clusters w $\sigma_v \approx 600$ km/s can be detected by WL but individual galaxies w $\sigma_v \approx 200$ km/s can not

$= 8.4 \sqrt{\frac{n}{30/\text{arcmin}^2}} \left(\frac{\sigma_\epsilon}{0.3}\right)^{-1} \left(\frac{\sigma_v}{600 \text{ km/s}}\right)^2 \sqrt{\frac{\ln(D_{out}/D_{in})}{\ln 10}} \underbrace{\left\langle \frac{D_{Ds}}{D_s} \right\rangle}$

cluster detection more difficult for increasing lens redshift (D_L larger $\Rightarrow D_{Ds}$ smaller)

Mean Tangential Shear on Circles

For axially symmetric lenses (§2.1)

$\gamma_1 = (x - \bar{x}) \cos 2\phi$
 $\gamma_2 = (x - \bar{x}) \sin 2\phi$ } $\gamma = (x - \bar{x}) e^{i2\phi}$

$\gamma_{\pm} = -\text{Re}(\gamma e^{-2i\phi}) = \bar{x} - x$

A similar relation holds for general matter distributions. Remember

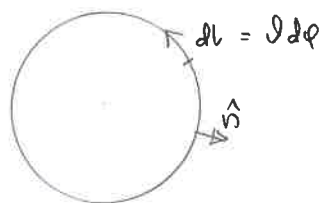
$\nabla^2 \psi = 2\kappa$

$\psi_{,11} = \kappa + \gamma_1$

$\psi_{,12} = \gamma_2$

$\psi_{,22} = \kappa - \gamma_1$

$\int_0^{\theta} \int_0^{\theta} \nabla^2 \psi = \int dl \nabla \psi \cdot \hat{n}$
 $= \int_0^{\theta} \int_0^{\theta} \frac{\partial \psi}{\partial \theta}$



dimensionless mass within radius θ : $m(\theta) \equiv \frac{1}{\pi} \int_0^{\theta} \int_0^{\theta} \kappa(\vec{\theta})$

we defined this earlier for the axisymmetric case; the factor $\frac{1}{\pi}$ is to match this earlier def.

$= \frac{\theta}{2\pi} \int_0^{\theta} \int_0^{\theta} \frac{\partial \psi}{\partial \theta}$

$\Rightarrow \frac{dm(\theta)}{d\theta} = \frac{m(\theta)}{\theta} + \frac{\theta}{2\pi} \int_0^{\theta} \frac{\partial^2 \psi}{\partial \theta^2}$

$\frac{\partial^2 \psi}{\partial \theta^2} = \kappa - \gamma_{\pm}$ generally

on the D_s axis this is $\psi_{,11} = \kappa + \gamma_1 = \kappa - \gamma_{\pm}$

$$\therefore \frac{dm(\varrho)}{d\varrho} = \frac{m(\varrho)}{\varrho} + \varrho \cdot \underbrace{\frac{1}{2\pi} \int_0^{2\pi} d\varphi (\kappa - \gamma_t)}_{\text{mean } \kappa - \gamma_t \text{ on circle w radius } \varrho} = \frac{m(\varrho)}{\varrho} + \varrho \cdot [\langle \kappa(\varrho) \rangle - \langle \gamma_t(\varrho) \rangle]$$

On the other hand, $\bar{\kappa}(\varrho) = \frac{1}{\pi\varrho^2} \int \varrho^2 d\varphi \kappa(\vec{\varrho}) = \frac{1}{\pi\varrho^2} \int_0^{2\pi} d\varphi \int_0^{\varrho} \varrho d\varrho \kappa(\vec{\varrho}) = \frac{m(\varrho)}{\varrho^2}$

$$= \frac{1}{\pi\varrho^2} \int_0^{\varrho} \varrho d\varrho \int_0^{2\pi} d\varphi \kappa(\varrho, \varphi)$$

$2\pi \langle \kappa(\varrho) \rangle$

for the axisymmetric case this gave $\frac{2}{\varrho^2}$ (p. 1-13)

$$\Rightarrow m(\varrho) = 2 \int_0^{\varrho} d\varrho' \varrho' \langle \kappa(\varrho') \rangle \Rightarrow \frac{dm(\varrho)}{d\varrho} = 2\varrho \langle \kappa(\varrho) \rangle$$

$$\therefore \varrho \langle \kappa(\varrho) \rangle = \frac{m(\varrho)}{\varrho} + \varrho \langle \kappa(\varrho) \rangle - \varrho \langle \gamma_t(\varrho) \rangle \Rightarrow \langle \kappa(\varrho) \rangle = \bar{\kappa}(\varrho) - \langle \gamma_t(\varrho) \rangle$$

$$\therefore \boxed{\langle \gamma_t \rangle = \bar{\kappa} - \langle \kappa \rangle}$$

where $\langle \rangle$ denotes average over circle w radius ϱ and $\bar{\kappa}$ is mean within this circle

\therefore From measurements of $\langle \gamma_t \rangle$ as a function of ϱ one can determine the azimuthally (φ)-averaged mass profile of lens (even if the lens is not axisymmetric).